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Chapter 14

### **MULTIPLE INTEGRATION**

#### 14.1 Summary

**Section 14.1 Iterated integrals and area in the plane** 1

### 1 Iterated integrals

(1) 
$$\int_{h_1(y)}^{h_2(y)} f_x(x,y) \, \mathrm{d}x = f(x,y) \, \Big|_{h_1(y)}^{h_2(y)} = f(h_2(y),y) - f(h_1(y),y)$$
 With respect to  $f(x,y) = f(x,y) \, \Big|_{h_1(y)}^{h_2(y)} = f(h_2(y),y) - f(h_1(y),y)$ 

(2) 
$$\int_{g_1(x)}^{g_2(x)} f_y(x,y) \, \mathrm{d}y = f(x,y) \Big|_{g_1(x)}^{g_2(x)} = f(x,g_2(x)) - f(x,g_1(x))$$
 With resp

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### 2. Area of a region in the plane

1. If R is defined by  $a \le x \le b$  and  $g_1(x) \le y \le g_2(x)$ , where  $g_1$  and  $g_2$  are continuous on [a,b], then the area of R is given by

$$A = \int_a^b \int_{g_1(x)}^{g_2(x)} dy dx.$$
 Figure ?? (vertically simple)

2. If R is defined by  $c \le y \le d$  and  $h_1(y) \le x \le h_2(y)$ , where  $h_1$  and  $h_2$  are continuous on [c,d], then the area of R is given by

$$A = \int_{c}^{d} \int_{h_{1}(y)}^{h_{2}(y)} dx dy.$$
 Figure ?? (horizontally simple)

3. **Double integral** If f defined on a closed, bounded region R in the xy-plane, then the **double integral** (二重積分) of f over R is given by

$$\iint_{R} f(x, y) dA = \lim_{\|\Delta\| \to 0} \sum_{i=1}^{n} f(x_i, y_i) \Delta A_i$$

provided the limit exists. If the limit exists, then f is over R..........9

4. Volume of a solid region (立體區域體積) If f is integrable over a plane region R and  $f(x,y) \geq 0$  for all (x,y) in R, then the volume of the solid region that lies above R and below the graph of f defined as

$$V = \iint_{R} f(x, y) \, \mathrm{d}A.$$

(

5. Properties of double integrals (二重積分性質) Let f and g be

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continuous over a closed, bounded plane region R, and let c be a constant.

- (a)  $\iint_R cf(x,y) dA = c \iint_R f(x,y) dA$
- (b)  $\iint_R [f(x,y) \pm g(x,y)] dA = \iint_R f(x,y) dA \pm \iint_R g(x,y) dA$
- (c)  $\iint_B f(x,y) dA \ge 0$ , if  $f(x,y) \ge 0$
- (d)  $\iint_R f(x,y) dA \ge \iint_R g(x,y) dA$ , if  $f(x,y) \ge g(x,y)$
- (e)  $\iint_R f(x,y) dA = \iint_{R_1} f(x,y) dA + \iint_{R_2} f(x,y) dA$ , where R is the union of two nonoverlapping subregions  $R_1$  and  $R_2$ .

- 6. Fubini's Theorem (富比尼定理) Let f be continuous on a plane region R.
  - (a) If R is defined by  $a \leq x \leq b$  and  $g_1(x) \leq y \leq g_2(x)$ , where  $g_1$  and

 $g_2$  are continuous on [a,b], then

$$\iint_{R} f(x,y) \, dA = \int_{a}^{b} \int_{g_{1}(x)}^{g_{2}(x)} f(x,y) \, dy \, dx.$$

(b) If R is defined by  $c \leq y \leq d$  and  $h_1(y) \leq x \leq h_2(y)$ , where  $h_1$  and  $h_2$  are continuous on [c,d], then

$$\iint_{R} f(x,y) \, dA = \int_{c}^{d} \int_{h_{1}(y)}^{h_{2}(y)} f(x,y) \, dx \, dy.$$

7. The average value of a function over a region If f is integrable over the plane region R, then the average value (平均値) of f over R is

$$\frac{1}{A} \iint_{R} f(x, y) \, \mathrm{d}A$$

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|    | where $A$ is the area of $R$   |  |
|----|--|--|
|    | Section 14.3 Change of variables: Polar coordinates 15   |  |
| 8. | 8. Change of variables to polar form Let $R$ be a plane region consisting of all points $(x,y)=(r\cos\theta,r\sin\theta)$ satisfying the condition $0\leq g_1(\theta)\leq r\leq g_2(\theta),\ \alpha\leq\theta\leq\beta$ , where $0\leq(\beta-\alpha)\leq2\pi$ . If $g$ and $g_2$ are continuous on $[\alpha,\beta]$ and $f$ is continuous on $R$ , then |  |
|    | $\iint_{R} f(x,y) dA = \int_{\alpha}^{\beta} \int_{g_{1}(\theta)}^{g_{2}(\theta)} f(r\cos\theta, r\sin\theta) r dr d\theta.$   |  |
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| 9. | Mass of a planar lamina of variable density $\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$  |  |

the mass m of the <u>lamina</u> (薄膜) is given by

$$m = \iint_{R} \rho(x, y) dA$$
. Variable density

## 10. Moments and center of mass of a variable density planar lamina

Let  $\rho$  be a continuous density function on the planar lamina R. The **moments of mass** (質矩) with respect to the x- and y-axes are

$$M_x = \iint_R y \rho(x,y) \, \mathrm{d}A$$
 and  $M_y = \iint_R x \rho(x,y) \, \mathrm{d}A.$ 

If m is the mass of the lamina, then the <u>center of mass</u> ( $\underline{\mathfrak{T}} \overset{\boldsymbol{\smile}}{\sim}$ ) is

$$(\overline{x},\overline{y}) = \left(\frac{M_y}{m}, \frac{M_x}{m}\right).$$

If R represents a simple plane region rather than a lamina, the point

11. Suppose a planar lamina is revolving about a line with an **angular speed** (角速度) of  $\omega$  radians per second. The kinetic energy E of the revolving lamina is

$$E = \frac{1}{2}I\omega^2$$
. Kinetic energy for rotational motion

12. On the other hand, the kinetic energy E of a mass m moving in a straight line at a velocity v is

$$E = \frac{1}{2}mv^2$$
. Kinetic energy for linear motion

The **radius of gyration** (旋轉半徑)  $\overline{r}$  of a revolving mass m with mo-

ment of inertia I is defined as

$$\overline{\overline{r}} = \sqrt{\frac{I}{m}}$$
. Radius of gyration

13. <u>Surface area</u> (曲面面積)] If f and its partial derivatives are continuous on the closed region R in the xy-plane, then the area of the surface S given by z = f(x, y) over R is defined as

Surface area = 
$$\iint_R dS = \iint_R \sqrt{1 + [f_x(x,y)]^2 + [f_y(x,y)]^2} dA.$$

**Section 14.6 Triple integrals and applications**...............................30

14. Triple integral If f is continuous over a bounded solid region Q, then the triple integral (三重積分) of f over Q is defined as

$$\iiint_Q f(x, y, z) dV = \lim_{\|\Delta\| \to 0} \sum_{i=1}^n f(x_i, y_i, z_i) \Delta V_i$$

provided the limit exists. The  $\underline{\text{volume}}$  (體積) of the solid region Q is given by

Volume of 
$$Q = \iiint_Q dV$$
.

15. Evaluation by iterated integrals Let f be continuous on a solid region Q defined by

$$a \le x \le b$$
,  $h_1(x) \le y \le h_2(x)$ ,  $g_1(x,y) \le z \le g_2(x,y)$ 

where  $h_1$ ,  $h_2$ ,  $g_1$ , and  $g_2$  are continuous functions. Then,

$$\iiint_Q f(x, y, z) \, dV = \int_a^b \int_{h_1(x)}^{h_2(x)} \int_{g_1(x, y)}^{g_2(x, y)} f(x, y, z) \, dz \, dy \, dx.$$

16. The <u>center of mass</u> ( $\underline{\mathfrak{T}}$ ) of a solid region Q of mass m is given by  $(\bar{x}, \bar{y}, \bar{z})$ , where

$$m = \iiint_Q \rho(x, y, z) \, dV, \ M_{yz} = \iiint_Q x \rho(x, y, z) \, dV, \ M_{xz} = \iiint_Q y \rho(x, y, z) \, dV$$

and

$$\bar{x} = \frac{M_{yz}}{m}, \quad \bar{y} = \frac{M_{xz}}{m}, \quad \bar{z} = \frac{M_{xy}}{m}.$$

17. The second moments (第二矩) (or moments of inertia (慣性矩))

about the x-, y-, and z-axes are as follows.

$$I_{x} = \iiint_{Q} (y^{2} + z^{2})\rho(x, y, z) \, dV, \ I_{y} = \iiint_{Q} (x^{2} + z^{2})\rho(x, y, z) \, dV, \ I_{z} = I_{xz} + I_{xy}, \quad I_{y} = I_{yz} + I_{xy}, \quad \text{and} \quad I_{z} = I_{yz} + I_{xz}$$

where  $I_{xy}$ ,  $I_{xz}$  and  $I_{yz}$  are as follows.

$$I_{xy} = \iiint_Q z^2 \rho(x, y, z) \, dV, \ I_{xz} = \iiint_Q y^2 \rho(x, y, z) \, dV, \ I_{yz} = \iiint_Q x^2 \rho(x, y, z) \, dV$$

18. The rectangular conversion equations for cylindrical coordinates (圓柱坐標)

are

$$x = r \cos \theta$$

$$x = r \cos \theta$$
  $y = r \sin \theta$   $z = z$ .

$$z=z$$
.

19. Triple integral in cylindrical coordinates: If R is r-simple, the iterated form of the triple integral in cylindrical form is

$$\iiint_{Q} f(x, y, z) dV = \int_{\theta_{1}}^{\theta_{2}} \int_{g_{1}(\theta)}^{g_{2}(\theta)} \int_{h_{1}(r\cos\theta, r\sin\theta)}^{h_{2}(r\cos\theta, r\sin\theta)} f(r\cos\theta, r\sin\theta, z) r dz dz$$

20. The rectangular conversion equations for spherical coordinates are

$$x = \rho \sin \phi \cos \theta$$
  $y = \rho \sin \phi \sin \theta$   $z = \rho \cos \phi$ .

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$
.

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21. Triple integral in spherical coordinates: Using the usual process involving an inner partition, summation, and a limit, you can develop the following version of a triple integral in spherical coordinates for a continuous function f defined on the solid region Q.

$$\iiint_{Q} f(x, y, z) \, dV = \int_{\theta_1}^{\theta_2} \int_{\phi_1}^{\phi_2} \int_{\rho_1}^{\rho_2} f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi \sin \theta$$

22. Jacobian If x=g(u,v) and y=h(u,v), then the <u>Jacobian</u> (雅可比) of x and y with respect to u and v, denoted by  $\partial(x,y)/\partial(u,v)$ ,

is

$$\frac{\partial(x,y)}{\partial(u,v)} = \left| \frac{\partial x}{\partial u} \frac{\partial x}{\partial v} \right| = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial y}{\partial u} \frac{\partial x}{\partial v}.$$

23. Change of variables for double integrals Let R be a vertically or horizontally simple region in the xy-plane, and let S be a vertically or horizontally simple region in the uv-plane. Let T from S to R be given by T(u,v)=(x,y)=(g(u,v),h(u,v)), where g and g have continuous first partial derivatives. Assume that T is one-to-one except possibly on the boundary of S. If f is continuous on R, and  $\partial(x,y)/\partial(u,v)$  is

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nonzero on S, then

$$\iint_{R} f(x,y) dx dy = \iint_{S} f(g(u,v), h(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv.$$
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24. **Gram determinant**: If  $x_i = x_i(t_1, \ldots, t_m)$ ,  $i = 1, 2, \ldots, n$ , then the **Gram determinant** (格拉姆行列式) of  $(x_1, x_2, \ldots, x_n)$  with respect to  $(t_1, \ldots, t_m)$  is

$$G = \det X^T X$$

where 
$$X = \partial(x_1, x_2, \dots, x_n) / \partial(t_1, t_2, \dots, t_m) = \begin{bmatrix} \frac{\partial x_1}{\partial t_1} & \frac{\partial x_1}{\partial t_2} & \cdots & \frac{\partial x_1}{\partial t_m} \\ \frac{\partial x_2}{\partial t_1} & \frac{\partial x_2}{\partial t_2} & \cdots & \frac{\partial x_2}{\partial t_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_n}{\partial t_1} & \frac{\partial x_n}{\partial t_2} & \cdots & \frac{\partial x_n}{\partial t_m} \end{bmatrix}.$$

25. Cauchy-Binet Formula (柯西-比内公式): Let A be an  $m \times n$  matrix and B an  $n \times m$  matrix. Then the determinant of their product C = AB can be written as a sum of products of minors of A and B:

$$|C| = \sum_{1 \le k_1 < k_2 < \dots < k_m \le n} A \begin{pmatrix} 1 & 2 & \dots & m \\ k_1 & k_2 & \dots & k_m \end{pmatrix} B \begin{pmatrix} k_1 & k_2 & \dots & k_m \\ 1 & 2 & \dots & m \end{pmatrix}.$$

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26. Change of variables for multiple integrals: Let  $\Omega$  be an m-dimensional region in  $\mathbb{R}^n$ ,  $m \leq n$ , and let  $\mathcal{T}$  be an m-dimensional region in  $\mathbb{R}^m$ . Let T from  $\mathcal{T}$  to  $\Omega$  be given by  $T(t_1,t_2,\ldots,t_m)=(x_1(t_1,t_2,\ldots,t_m),x_2(t_1,t_2,\ldots,t_m),\ldots,x_n(t_1,t_2,\ldots,t_m))$ , where  $g_i$ 's have continuous first partial derivatives. Assume that T is one-to-one except possibly on the boundary of  $\mathcal{T}$ . If f is continuous on  $\Omega$ , and G is nonzero on  $\mathcal{T}$ , then

$$\int \cdots \int_{\Omega} f(x_1, \dots, x_n) \, dV = \int \cdots \int_{\mathcal{T}} f(x_1(t_1, \dots, t_m), \dots, x_n(t_1, \dots, t_m))$$

27. Volume of an m-dimensional region in  $\mathbb{R}^n$ ,  $m \leq n$ : Let  $\Omega$  be an m-dimensional region in  $\mathbb{R}^n$ ,  $m \leq n$ , and let  $\mathcal{T}$  be an m-dimensional region in  $\mathbb{R}^m$ . Let T from  $\mathcal{T}$  to  $\Omega$  be given by  $T(t_1, t_2, \ldots, t_m) =$ 

 $(x_1(t_1,t_2,\ldots,t_m),x_2(t_1,t_2,\ldots,t_m),\ldots,x_n(t_1,t_2,\ldots,t_m))$ , where  $g_i$ 's have continuous first partial derivatives. Assume that T is one-to-one except possibly on the boundary of  $\mathcal T$  and G is nonzero on  $\mathcal T$ . Then the volume of  $\Omega$  is

$$\int \cdots \int_{\Omega} dV = \int \cdots \int_{\mathcal{T}} \sqrt{G} dt_m \cdots dt_1.$$

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