Chapter 11 Vectors and the Geometry of Space

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2 Cylindrical and spherical coordinates

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Cylindrical surfaces

• You have already known two special types of surfaces.

Spheres:
$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$

Planes:
$$ax + by + cz + d = 0$$

- A third type of surface in space is called a cylindrical surface, or simply a cylinder.
- To define a cylinder, consider the familiar right circular cylinder shown in Figure 1.

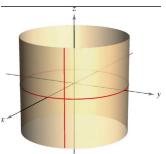


Figure 1: Right circular cylinder: $x^2 + y^2 = a^2$. Rulings are parallel to the z-axis.

- You can imagine that this cylinder is generated by a vertical line moving around the circle $x^2 + y^2 = a^2$ in the *xy*-plane.
- This circle is called a generating curve for the cylinder, as indicated in the following definition

Definition 11.1 (Cylinder)

Let C be a curve in a plane and let L be a line not in a parallel plane. The set of all lines parallel to L and intersecting C is called a cylinder. C is called the generating curve (or **directrix**) of the cylinder, and the parallel lines are called rulings.

• For the right circular cylinder shown in Figure 1, the equation of the generating curve is

 $x^2 + y^2 = a^2$. Equation of generating curve in xy-plane

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- To find an equation of the cylinder, note that you can generate any one of the rulings by fixing the values of x and y and then allowing z to take on all real values.
- In this sense, the value of z is arbitrary and is, therefore, not included in the equation.
- In other words, the equation of this cylinder is simply the equation of its generating curve.

 $x^2 + y^2 = a^2$ Equation of cylinder in space

Definition 11.2 (Equation of cylinders)

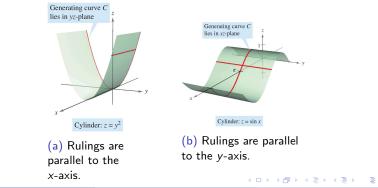
The equation of a cylinder whose ruling are parallel to one of the coordinate axes contain only the variables corresponding to the other two axes.

Example 1 (Sketching a cylinder)

Sketch the surface represented by each equation.

a.
$$z = y^2$$
 b. $z = \sin x$, $0 \le x \le 2\pi$.

- The graph is a cylinder whose generating curve, z = y², is a parabola in the yz-plane.
 - The rulings of the cylinder are parallel to the x-axis.
- **b.** The graph is a cylinder generated by the sine curve in the *xz*-plane.
 - The rulings are parallel to the y-axis.



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Quadric surfaces

- The fourth basic type of surface in space is a quadric surface.
- Quadric surfaces are the three-dimensional analogs of conic sections.

Definition 11.3 (Quadric surface)

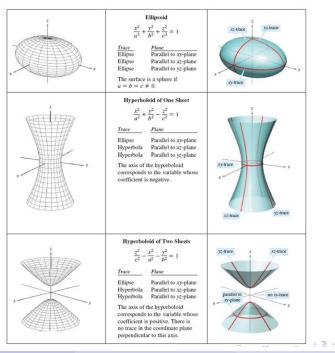
The equation of a quadric surface in space is a second-degree equation in three variables. The general form of the equation is

$$Ax2 + By2 + Cz2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0.$$

There are six basic types of quadric surfaces: ellipsoid, hyperboloid of one sheet, hyperboloid of two sheets, elliptic cone, elliptic paraboloid, and hyperbolic paraboloid.

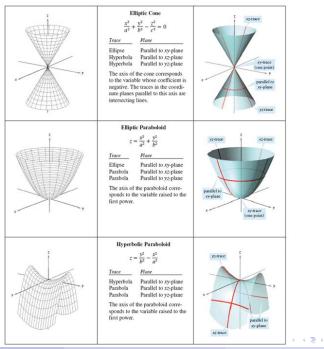
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- The intersection of a surface with a plane is called the trace of the surface in the plane.
- To visualize a surface in space, it is helpful to determine its traces in some well-chosen planes.
- The traces of quadric surfaces are conics.
- These traces, together with the standard form of the equation of each quadric surface, are shown in the following table.



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Example 2 (Sketching a quadric surface)

Classify and sketch the surface given by

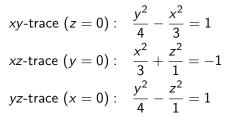
$$4x^2 - 3y^2 + 12z^2 + 12 = 0.$$

• Begin by writing the equation in standard form.

$$4x^{2} - 3y^{2} + 12z^{2} + 12 = 0$$
$$\frac{x^{2}}{-3} + \frac{y^{2}}{4} - z^{2} - 1 = 0$$
$$\frac{y^{2}}{4} - \frac{x^{2}}{3} - \frac{z^{2}}{1} = 1$$

• You can conclude that the surface is a hyperboloid of two sheets with the *y*-axis as its axis.

• To sketch the graph of this surface, it helps to find the traces in the coordinate planes.



No trace

Hyperbola

Hyperbola

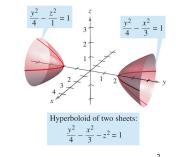


Figure 3: Hyperboloid of two sheets: $\frac{y^2}{4} - \frac{x^2}{3} - \frac{z^2}{4} = 1$

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Example 3 (Sketching a quadric surface)

Classify and sketch the surface given by $x - y^2 - 4z^2 = 0$.

- Because x is raised only to the first power, the surface is a paraboloid.
- The axis of the paraboloid is the x-axis. In the standard form, the equation is

$$x = y^2 + 4z^2.$$

• Some convenient traces are as follows.

xy-trace
$$(z = 0)$$
: $x = y^2$ Parabola
xz-trace $(y = 0)$: $x = 4z^2$ Parabola
parallel to yz-plane $(x = 4)$: $\frac{y^2}{4} + \frac{z^2}{1} = 1$ Ellipse

• The surface is an elliptic paraboloid, as shown in Figure 4.

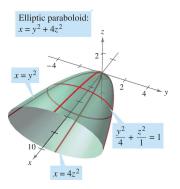


Figure 4: Elliptic paraboloid.

Example 4 (A quadric surface not centered at the origin)

Classify and sketch the surface given by $x^2 + 2y^2 + z^2 - 4x + 4y - 2z + 3 = 0.$

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• Completing the square for each variable produces the following.

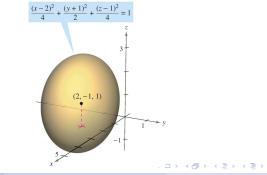
$$(x^{2} - 4x +) + 2(y^{2} + 2y +) + (z^{2} - 2z +) = -3$$

$$(x^{2} - 4x + 4) + 2(y^{2} + 2y + 1) + (z^{2} - 2z + 1) = -3 + 4 + 2 + 1$$

$$(x - 2)^{2} + 2(y + 1)^{2} + (z - 1)^{2} = 4$$

$$\frac{(x - 2)^{2}}{4} + \frac{(y + 1)^{2}}{2} + \frac{(z - 1)^{2}}{4} = 1$$

• From this equation, you can see that the quadric surface is an ellipsoid that is centered at (2, -1, 1).



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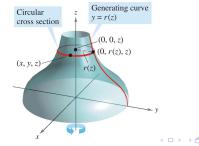
Surfaces of revolution

- The fifth special type of surface you will study is called a surface of revolution.
- You will now look at a procedure for finding its equation.
- Consider the graph of the radius function

$$y = r(z)$$
 Generating curve

in the *yz*-plane.

 If this graph is revolved about the z-axis, it forms a surface of revolution.



• The trace of the surface in the plane $z = z_0$ is a circle whose radius is $r(z_0)$ and whose equation is

 $x^2 + y^2 = [r(z_0)]^2$. Circular trace in plane: $z = z_0$

- Replacing z_0 with z produces equation that is valid for all values of z.
- You can obtain equations for surfaces of revolution for the other two axes, and the results are summarized as follows.

Definition 11.4 (Surface of revolution)

If the graph of a radius function r is revolved about one of the coordinate axes, the equation of the resulting surface of revolution has one of the following forms.

- Revolved about the x-axis: $y^2 + z^2 = [r(x)]^2$
- 2 Revolved about the y-axis: $x^2 + z^2 = [r(y)]^2$
- S Revolved about the z-axis: $x^2 + y^2 = [r(z)]^2$

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Example 5 (Finding an equation for a surface of revolution)

Find an equation for the surface of revolution formed by revolving (a) the graph of y = 1/z about the *z*-axis and (b) the graph of $9x^2 = y^3$ about the *y*-axis.

a. An equation for the surface of revolution formed by revolving the graph of $y = \frac{1}{z}$ (radius function) about the z-axis is

$$x^{2} + y^{2} = [r(z)]^{2}$$
 $x^{2} + y^{2} = \left(\frac{1}{z}\right)^{2}$

b. To find an equation for the surface formed by revolving the graph of $9x^2 = y^3$ about the *y*-axis, solve for *x* in terms of *y* to obtain $x = \frac{1}{3}y^{3/2} = r(y)$ (radius function). So, the equation for surface is

$$x^{2} + z^{2} = [r(y)]^{2}$$
 $x^{2} + z^{2} = \left(\frac{1}{3}y^{3/2}\right)^{2}$ $x^{2} + z^{2} = \frac{1}{9}y^{3}$

The graph is shown in Figure 5.

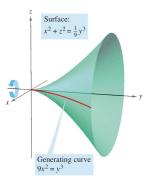


Figure 5: Surface of revolution: $x^2 + z^2 = \frac{1}{9}y^3$ with generating curve $9x^2 = y^3$ about the *y*-axis.

Example 6 (Finding a generating curve for a surface of revolution)

Find a generating curve and the axis of revolution for the surface given by

$$x^2 + 3y^2 + z^2 = 9.$$

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• You now know that the equation has one of the following forms.

$x^2 + y^2 = [r(z)]^2$	Revolved about <i>z</i> -axis
$y^2 + z^2 = [r(x)]^2$	Revolved about x-axis
$x^2 + z^2 = [r(y)]^2$	Revolved about y-axis

• Because the coefficients of x^2 and z^2 are equal, you should choose the third form and write

$$x^2 + z^2 = 9 - 3y^2.$$

- The y-axis is the axis of revolution.
- You can choose a generating curve from either of the following traces.

$$x^2 = 9 - 3y^2$$
Trace in xy-plane $z^2 = 9 - 3y^2$ Trace in yz-plane

• For example, using the first trace, the generating curve is the semiellipse given by

$$x=\sqrt{9-3y^2}.$$

• The graph of this surface is shown in Figure 6.

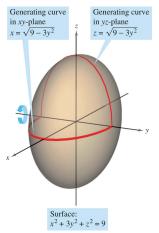


Figure 6: Finding a generating curve for a surface of revolution: not unique.

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• The cylindrical coordinate system, is an extension of polar coordinates in the plane to three-dimensional space.

Definition 11.5 (The cylindrical coordinate system)

In a cylindrical coordinate system, a point P in space is represented by an ordered triple (r, θ, z) .

- **(** (r, θ) is a polar representation of the projection of *P* in the *xy*-plane.
- 2 *z* is the directed distance from (r, θ) to *P*.

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• To convert from rectangular to cylindrical coordinates (or vice versa), use the following conversion guidelines for polar coordinates, as illustrated in Figure 7.

$$x = r \cos \theta$$
, $y = r \sin \theta$, $z = z$
 $r^2 = x^2 + y^2$, $\tan \theta = \frac{y}{x}$, $z = z$

• The point (0,0,0) is called the pole.

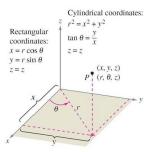


Figure 7: The relationship between cylindrical and rectangular coordinates.

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• Moreover, because the representation of a point in the polar coordinate system is not unique, it follows that the representation in the cylindrical coordinate system is also not unique.

Example 1 (Converting from cylindrical to rectangular coordinates)

Convert the point $(r, \theta, z) = (4, \frac{5\pi}{6}, 3)$ to rectangular coordinates.

• Using the cylindrical-to-rectangular conversion equations produces

$$x = 4\cos\frac{5\pi}{6} = 4\left(-\frac{\sqrt{3}}{2}\right) = -2\sqrt{3}$$
$$y = 4\sin\frac{5\pi}{6} = 4\left(\frac{1}{2}\right) = 2$$
$$z = 3.$$

• So, in rectangular coordinates, the point is $(x, y, z) = (-2\sqrt{3}, 2, 3)$ as shown in Figure 8.

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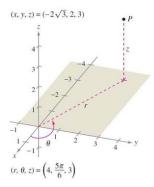


Figure 8: Converting $(r, \theta, z) = (4, \frac{5\pi}{6}, 3)$ to $(x, y, z) = (-2\sqrt{3}, 2, 3)$.

Example 2 (Converting from rectangular to cylindrical coordinate)

Convert the point $(x, y, z) = (1, \sqrt{3}, 2)$ to cylindrical coordinates.

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• Use the rectangular-to-cylindrical conversion equations.

$$r = \pm \sqrt{1+3} = \pm 2$$

$$\tan \theta = \sqrt{3} \implies \theta = \arctan(\sqrt{3}) + n\pi = \frac{\pi}{3} + n\pi$$

$$z = 2$$

- You have two choices for r and infinitely many choices for θ .
- As shown in Figure 9, two convenient representations of the point are

$$\left(2, \frac{\pi}{3}, 2\right)$$
 $r > 0$ and θ in Quadrant I
 $\left(-2, \frac{4\pi}{3}, 2\right)$. $r < 0$ and θ in Quadrant III

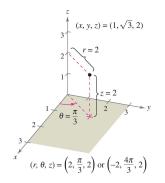


Figure 9: Converting from rectangular to cylindrical coordinates.

- Cylindrical coordinates are especially convenient for representing cylindrical surfaces and surfaces of revolution with the *z*-axis as the axis of symmetry, as shown in Figure 10.
- Vertical planes containing the *z*-axis and horizontal planes also have simple cylindrical coordinate equations, as shown in Figure 11.

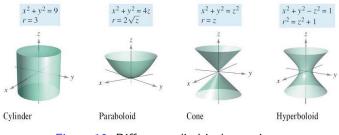


Figure 10: Different cylindrical equations.

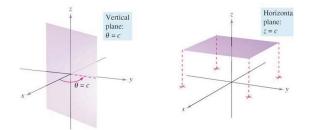


Figure 11: Vertical plane: $\theta = c$ and horizontal plane: z = c.

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Example 3 (Rectangular-to-cylindrical conversion)

Find an equation in cylindrical coordinates for the surface represented by each rectangular equation.

a.
$$x^2 + y^2 = 4z^2$$
 b. $y^2 = x$

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a. From the preceding section, you know that the graph $x^2 + y^2 = 4z^2$ is an elliptic cone with its axis along the *z*-axis, as shown in Figure 12(a). If you replace $x^2 + y^2$ with r^2 , the equation in cylindrical coordinates is

$$x^2 + y^2 = 4z^2 \qquad r^2 = 4z^2.$$

b. The graph of the surface $y^2 = x$ is a parabolic cylinder with rulings parallel to the *z*-axis, as shown in Figure 12(b). By replacing y^2 with $r^2 \sin^2 \theta$ and x with $r \cos \theta$, you obtain the following equation in cylindrical coordinates.

$$y^{2} = x \qquad r^{2} \sin^{2} \theta = r \cos \theta \qquad r(r \sin^{2} \theta - \cos \theta) = 0$$

$$r \sin^{2} \theta - \cos \theta = 0 \qquad r = \frac{\cos \theta}{\sin^{2} \theta} \qquad r = \csc \theta \cot \theta$$
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Note that this equation includes a point for which r = 0, so nothing was lost by dividing each side by the factor r.

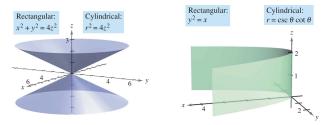


Figure 12: Rectangular-to-cylindrical conversion.

Example 4 (Cylindrical-to-rectangular conversion)

Find an equation in rectangular coordinates for the surface represented by the cylindrical equation

$$r^2\cos 2\theta + z^2 + 1 = 0.$$

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$$r^{2}\cos 2\theta + z^{2} + 1 = 0$$

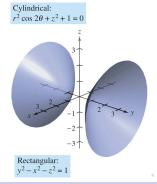
$$r^{2}(\cos^{2}\theta - \sin^{2}\theta) + z^{2} = -1$$

$$r^{2}\cos^{2}\theta - r^{2}\sin^{2}\theta + z^{2} = -1$$

$$x^{2} - y^{2} + z^{2} = -1$$

$$y^{2} - x^{2} - z^{2} = 1$$

This is a hyperboloid of two sheets whose axis lies along the y-axis.



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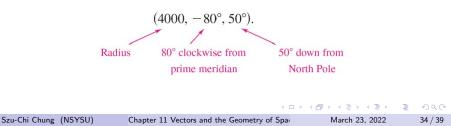
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Spherical coordinates

- In the spherical coordinate system, each point is represented by an ordered triple: the first coordinate is a distance, and the second and third coordinates are angles.
- This system is similar to the latitude-longitude system used to identify points on the surface of Earth.
- For example, the point on the surface of Earth whose latitude is 40° North (of the equator) and whose longitude is 80° West (of the prime meridian) is shown in Figure 14. Assuming that the Earth is spherical and has a radius of 6371 kilometers, you would label this point as



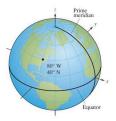


Figure 14: Spherical coordinate of 80° W 40° N is $(4000, -80^{\circ}, 50^{\circ})$.

Definition 11.6 (The spherical coordinate system)

In a spherical coordinate system, a point P in space is represented by an ordered triple (ρ, θ, ϕ) .

- 1. ρ is the distance between P and the origin, $\rho \ge 0$.
- 2. θ is the same angle used in cylindrical coordinates for $r \ge 0$.
- 3. ϕ is the angle between the positive *z*-axis and the line segment \overrightarrow{OP} , $0 \le \phi \le \pi$.

Note that the first and third coordinates, ρ and ϕ , are nonnegative. ρ is the lowercase Greek letter rho, and ϕ is the lowercase Greek letter phi.

• The relationship between rectangular and spherical coordinates is illustrated in Figure 15.

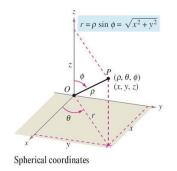


Figure 15: The relationship between rectangular coordinate (x, y, z) and spherical coordinates (ρ, θ, ϕ) where $r = \rho \sin \phi = \sqrt{x^2 + y^2}$.

- To convert from one system to the other, use the following.
- Spherical to rectangular:

$$x = \rho \sin \phi \cos \theta$$
, $y = \rho \sin \phi \sin \theta$, $z = \rho \cos \phi$.

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• Rectangular to spherical:

$$ho^2 = x^2 + y^2 + z^2$$
, $an \theta = \frac{y}{x}$, $\phi = \arccos\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right)$

- To change coordinates between the cylindrical and spherical systems, use the following.
- Spherical to cylindrical $(r \ge 0)$:

$$r^2 = \rho^2 \sin^2 \phi, \quad \theta = \theta, \quad z = \rho \cos \phi.$$

• Cylindrical to spherical $(r \ge 0)$:

$$ho = \sqrt{r^2 + z^2}, \quad heta = heta, \quad \phi = \arccos\left(rac{z}{\sqrt{r^2 + z^2}}
ight).$$

- The spherical coordinate system is useful primarily for surfaces in space that have a point or center of symmetry.
- For example, Figure 16 shows three surfaces with simple spherical equations.

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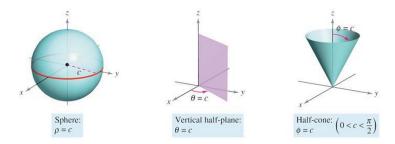


Figure 16: Three surfaces with simple spherical equations.

Example 5 (Rectangular-to-spherical conversion)

Find an equation in spherical coordinates for the surface represented by each rectangular equation.

a. Cone:
$$x^2 + y^2 = z^2$$
 b. Sphere: $x^2 + y^2 + z^2 - 4z = 0$

a. Making the appropriate replacements for x, y, and z in the given equation yields the following.

$$\begin{aligned} x^2 + y^2 &= z^2 \\ \rho^2 \sin^2 \phi \cos^2 \theta + \rho^2 \sin^2 \phi \sin^2 \theta &= \rho^2 \cos^2 \phi \\ \rho^2 \sin^2 \phi (\cos^2 \theta + \sin^2 \theta) &= \rho^2 \cos^2 \phi \\ \rho^2 \sin^2 \phi &= \rho^2 \cos^2 \phi \\ \frac{\sin^2 \phi}{\cos^2 \phi} &= 1 \qquad \rho \ge 0 \\ \tan^2 \phi &= 1 \qquad \phi = \pi/4 \text{ or } \phi = 3\pi/4 \end{aligned}$$

The equation $\phi = \pi/4$ represents the upper half-cone, and the equation $\phi = 3\pi/4$ represents the lower half-cone.

b. Because $\rho^2 = x^2 + y^2 + z^2$ and $z = \rho \cos \phi$, the given equation has the following spherical form.

$$\rho^2 - 4\rho\cos\phi = 0 \implies \rho(\rho - 4\cos\phi) = 0 \implies \rho(\rho - 4\cos\phi) = 0$$

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$$\rho - 4\cos\phi = 0$$
 or $\rho = 4\cos\phi$.

Note that the solution set for this equation includes a point for which $\rho = 0$, so nothing is lost by discarding the factor ρ . The sphere represented by the equation $\rho = 4 \cos \phi$ is below.

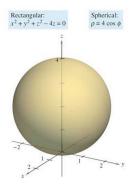


Figure 17: $x^2 + y^2 + z^2 - 4z = 0$ in rectangular coordinate is equivalent to $\rho = 4 \cos \phi$ in spherical coordinate.